#### **Future trends/ Concerns**

- Positive and negative effects of local, state, and federal regulations on use of unmanned systems
- More issues will arise with maintaining traffic management as the number of unmanned vehicles in use increases
- Drone-in-a-box (like scooters in a city) will increase drone-as-a-service use in industry (i.e., security industry)
- Emergence of artificial intelligence and increases in autonomy of drones will allow for on-demand mobility and delivery (i.e., self-driving cars and taxis, delivery of food and packages, etc.)
- Sensor advancements will increase capabilities and/or situational awareness
- BVLOS will enable UAS industry expansion and impact roles/responsibilities in UAS occupations
- With increased autonomy of systems, we run the risk of issues arising from humans not paying as close attention.
- Manufacturers are working on hybrid transportation mode or "pop up" vehicles (i.e. AirBus, Audi, and Porsche)
- Advancements in the industry will lead to additional legal implications and liability concerns with unmanned systems use
- Infrastructure necessary to implement BVLOS, extended capabilities, etc. needs to be in place first; the lack of broadband in many areas (especially rural) will limit expansion of UAS industry
- Need to develop test sites in VA for underwater unmanned vehicles

#### **Definitions of Acronyms**

AI	Artificial Intelligence	PPE	Personal Protective Equipment
AR	Augmented Reality	РРК	Post-Processed Kinematic
ATV	All-Terrain Vehicle	RF	Radio Frequency
BVLOS	Beyond Visual Line of Sight	RTK	Real-Time Kinematic
CAD	Computer-Aided Design	SD	Secure Digital
CAN	Controller Area Network	SPI	Serial Peripheral Interface
CTD	Conductivity Temperature Depth	SQL	Structured Query Language
ESC	Electronic Speed Controllers	SWAP	Size Weight and Power
FOD	Foreign Object and Debris	UAS	Unmanned Aircraft System
FPV	First-Person View	sUAS	Small Unmanned Aircraft System
GIS	Geographical Information System		
GNSS	Global Navigation Satellite System		
GPS	Global Position Satellite		

- Inertial Measurement Unit IMU
- IP **Ingress Protection**
- ITAR International Traffic in Arms Regulations
- Inter-Integrated Circuit 12C
- Low Altitude Authorization and Notification Capability LAANC
- LED Light-Emitting Diode
- LIDAR Light Detection and Ranging
- Normalized Difference Vegetation Index NDVI
- Occupational Safety and Health Administration **OSHA**
- PDB **Power Distribution Boards**

# THOMAS NELSON The Peninsula's Community College **GeoTEd-UAS** VIRGINIA SPACE GRANT CONSORTIUM **RESOURCES AND ENVIRONMENT** #1601614 Produced & Facilitated by

### **DACUM** Panel

# **DACUM Research Chart Unmanned Systems Technician** Marco Sterk, President & Founder The Longbow Group/Express Drone Parts LLC Daniel Cross, UAS/GIS Operator Conservation Management Institute, Virginia Tech David Hare, Equipment Specialist NASA Langley Research Center Jeanna Kidwell, Operations Director Coastal and Polar Physical Oceanography Lab Virginia Institute of Marine Science, College of William and Mary Mike Ihirg, CEO **MI Technical Solutions** David Barton, Director of Aerial Services & Chief Pilot **Project Points of Contact** Chérie A. Aukland, GISP, FAA RPC Co-PI GeoTEd-UAS Associate Professor of IST, Program Head for GIS auklandc@tncc.edu Julie A. Young, FAA RPC

Draper Aden Associates

Mechanical Engineering Technology Program Head **UnManned Systems Program Head** youngj@tncc.edu

This initiative was paid for in part by a federal U.S. Department of Labor, Employment and Training Administration Workforce Innovation and Opportunity Act (WIOA) award made to Thomas Nelson Community College by the pass-through entity, Virginia Community College System.

Jennifer Stevens President & CEO www.virginiaedstrategies.org



## DACUM Research Chart Unmanned Systems Technician

A.01 Identify require (i.e., de objectiv A.16 mission Deconf resourc person	A.02 fy mission Identify an ements operation eliverables, ives, etc.) A.17 iflict mission Monitor w rces (i.e., conditions nnel time	A.03 as of Identify time of operations A.18 ather Obtain required permits	A.04 Identify unmanned systems to use A.19 Create mission readiness plan	A.05 d Determine permits required for mission A.20 Create crew management plan	A.06 Conduct safety assessment A.21 Assemble unmanned vehicle systems*	A.07 Develop safety plan A.22 Report issues to management	A.08 Conduct risk assessment	A.09 Develop risk mitigation plan	A.10 Determine technical feasibility of mission	A.11 Determine operational feasibility of mission	A.12 Perform site survey*	A.13 Define operational limits	A.14 Determine ground support needs	A.15 Develop operation budget
B.01 B.01 Commu stakeho Coordinate operational B.16	B.02 B.02 nunicate with Schedule s nolders access B 17	B.03 e Coordinate local security requirements	B.04 Schedule personnel	B.05 Obtain software	B.06 Obtain hardware	B.07 Obtain ground support equipment	B.08 Obtain vendor quotes	B.09 Purchase system components	B.10 Obtain ancillary data	B.11 Load map data	B.12 Create packing list	B.13 Ship mission equipment	B.14 Secure site- specific resources (i.e., local fishing boat, data plan, etc.)	B.15 Secure environment- specific resources (i.e., battery protection, ATV.
logistics Facilita personi (i.e., for shelter,	ate Manage tr nnel needs logistics ood, water, r, etc.)	vel												cold-weather gear, etc.)
C.01 Maintain Perform unmanned progres vehicle systems inspect	C.02 rm Research essive manufactu stions specificatio	C.03 Monitor er manufacturer for ns updates	C.04 Perform manufacturer- recommended updates	C.05 Check manufacturer warranties	C.06 Maintain logbook entries	C.07 Verify unmanned vehicle registrations	C.08 Dissassemble unmanned vehicle systems*	C.09 Repair/replace components*	C.10 Calibrate equipment	C.11 Test system components	C.12 Maintain spare parts	C.13 Maintain system diagrams	C.14 Maintain vehicle air/sea- worthiness	C.15 Verify vehicle performance
Maintain D.01 unmanned Inspect vehicle power systems	D.02 t batteries Charge bat mage	D.03 eries Storage-charge batteries	D.04 Store batteries in lipo-safe container	D.05 Verify battery capacity	D.06 Log cell voltages	D.07 Track battery cycles	D.08 Dispose of dead batteries	D.09 Maintain battery chargers	D.10 Mix fuel	D.11 Test quality of fue	D.12 Fill fuel containers	D.13 Store fuel in controlled environment	D.14 Change engine oil	I
E.01 Review manual Unmanned vehicle payloads Bencht	E.02 w specs and Identify int als requireme E.17 test system Check cent	E.03 erface Identify SWAP ts E.18 er of Ballast glider for	E.04 Document payloads integrated configuration E.19 Update	E.05 Configure glider mission & data acquisition commands E.20 Calibrate sensors	E.06 Run interference tests* E.21 Verify IP has been	E.07 Identify data storage device E.22 Verify vibration	E.08 Fabricate wiring harnesses E.23 Perform power-up	E.09 Test wiring harnesses E.24 Replace and lube	E.10 Define mounting requirements E.25 Update	E.11 Fabricate mounting hardware	E.12 Test mounting hardware	E.13 Test subcomponents	E.14 Benchtest software	E.15 Benchtest subsystem
F.01	gravity F.02	target water density F.03	weight and balance documentation F.04	F.05	maintained F.06	levels F.07	F.08	o-rings F.09	maintenance records F.10	F.11	F.12			
Perform pre- pre-mis checklis	op Perform ission ground-to- list system che	Verify mission nit time (i.e., flight cks time, vehicle endurance, etc.)	Update mission log	Establish mission boundaries (e.g., geofencing)	Determine mission fuel needs	Test navigation systems	Load payload software	Create spare parts list	Troubleshoot issues	Run mission simulation	Perform mission acceptance test (i.e. flight, launch, etc.)			
G.01 Execute Run pre unmanned checklis systems mission	G.02 re-mission Unpack mi list equipment	G.03 sion Check packing lis	G.04 Set-up field site	G.05 Secure mission site	G.06 Perform FOD checks	G.07 Identify alternate recovery sites	G.08 Conduct safety briefing	G.09 Conduct mission briefing	G.10 Conduct weather briefing	G.11 Establish radio communications	G.12 Perform mission- specific duties	G.13 Launch unmanned vehicle	G.14 Recover unmanned vehicle	G.15 Conduct post- mission briefing
H.01 Manage Retriev data data	H.02 ve captured Back-up ca data*	H.03 tured Index captured data	H.04 Verify data quality	H.05 Post-process captured data	H.06 Validate data satisfies requirements	H.07 Maintain physical security of data								
I.01 Maintain Obtain professional license knowledge	I.02 n UAS pilot Obtain par e license (sU	I.03 107 Obtain required S) certifications	I.04 Stay abreast of technological advances	I.05 Attend professional development	I.06 Review manufacturer literature	I.07 Attend trade shows	I.08 Participate in community outreach	I.09 Participate in industry user groups	I.10 Take platform- specific courses	I.11 Train colleagues	I.12 Participate in safety training	I.13 Comply with operations manual	I.14 Stay abreast of current regulations	l.15 Maintain proficiency